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<b>KLM Technology Group</b> #03-12 Block Aronia, Jalan Sri Perkasa 2 Taman Tampoi Utama 81200 Johor Bahru Malaysia	<b>Kolmetz Handbook of Process Equipment Design</b>  <b>Instrumentation Selection, Sizing and Troubleshooting</b>  <b>(Engineering Design Guidelines)</b>	Co Author Rev 01 - A L Ling Rev 02 - Viska Mulyandasari Rev 03 - K Kolmetz Rev 04- Mochamad Adha Firdaus  Editor / Author  <b>Karl Kolmetz</b>

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## **INTRODUCTION**

### **Scope**

Instrumentation is a term that is commonly used in engineering, which means measurement and control for industrial process systems. Various processes in petrochemical industries need to be maintained at controlled levels to get the desired product. It is commonly done by controlling such process variables as pressure, temperature, and liquid level by using measurement devices (instruments) with control systems. Control instrumentation plays a significant role in both gathering information from the field and changing the field parameters.

This design guideline covers the selection of measurement devices and control systems which are commonly used in the processing industries. Measurement devices could be classified into various types based on their function.

In this guideline, three types of commonly used measurement devices are explained in detail; such as pressure, level, and temperature measurement devices. Some devices, such as signal transmitter, recorder, and indicator, are generally also networked together to support the measurement device. Those supporting equipments are also explained as well in this guideline.

The selection of measurement device is mostly based on necessity, which variables need to be controlled. But their accuracy, installation cost, and maintenance should be considered as well. Comparing several measurement devices might be important to obtain the most suitable one.

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Besides deciding the measurement device to be used in a process, it is also important to put them in a right order. Hence, the control system and control mode explanation are also included in this guideline.

The control system decides how to cope the disturbances in process system by managing behavior of other devices in a system. Generally a controller could be classified into several types based on its characteristics. Each type of controller has their own disadvantages; hence they are commonly combined in industrial process system. No one control system and controller can be utilized for all petrochemical industrial applications. This guideline gives the basic information as a guide to be applied in the process industries.

Some sample calculations based on the real industrial samples are included in this guideline. Calculation spreadsheet for manometer, level measurement using pressure gauge devices and Bimetal thermometers are attached as well and to aid user to understand how to apply the theory for calculations.

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## General Concept of Instrumentation

An instrument is a device that transforms a physical variable (temperature, length, pressure, velocity, capacity, etc) of interest (the measurand) into a form that is suitable for recording (the measurement). In order for the measurement to have broad and consistent meaning, it is common to employ a standard system of units by which the measurement from one instrument can be compared with the measurement of another. An example of a basic instrument is a ruler. In this case the measurand is the length of some object and the measurement is the number of units (meters, inches, etc.) that represent the length.<sup>(4)</sup>

Simple instrument model (Figure 1), physical measurement variable is measure by measurand as input to sensor; sensor has a function to convert the input to signal variable; signal variables have the property that they can be manipulated in a transmission system, the signal is transmitted to a display or recording device where the measurement can be read by a human observer.

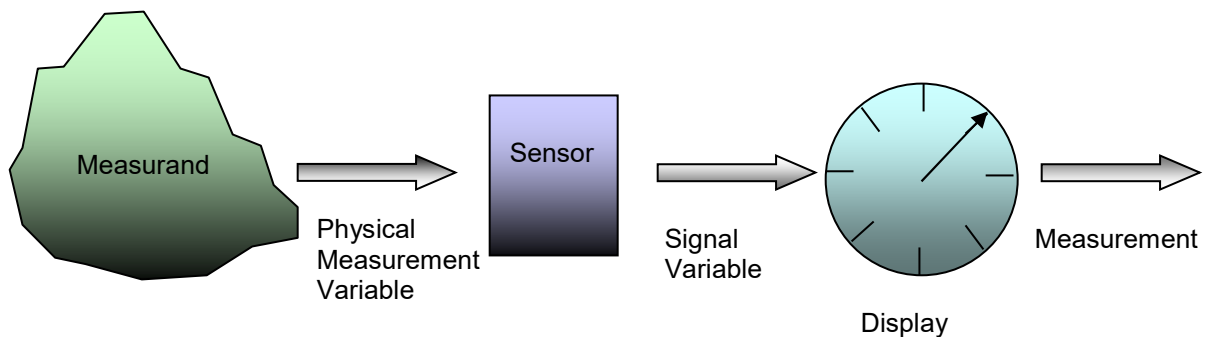


Figure 1: Simple Instrument Model

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Instruments are important for control of process variables (temperature, pressure, level, flow and etc). Objectives of process control are to achieve safe production, lowest cost of process, improving product quality, lowering labor costs, reducing or eliminating human error, reducing energy consumption, elimination of product giveaway, and reducing products off-spec.

Instrumentation in industrial sites today normally are equipped with a distributed control system (DCS) that provides advanced control capabilities and interfaces to other systems, including management information and accounting systems and read-only interface to protective systems.

Function of the process control can be class into basic functions and corollary functions. Generally basic functions are needed for plant operability and corollary functions come after plant operability is established.

Basic functions consist of maintaining stability of operating conditions at key points in the process and providing the operator with information of suitable operating condition and the means for adjusting them.

The corollary functions are automating operations which reduce the demand for continuous operator attention as dictated by economics; insuring that operations are safe for personnel and equipment to met all regulatory requirements; and maintaining product quality while minimizing operating costs.

Instrumentation is usually comprised of a system of pneumatic or electronic devices for measurement and control of all the process variables. Both type of the pneumatic or electronic instrumentation have advantages and disadvantages.

Generally advantage of pneumatic system is intrinsically safe (no electrical circuits), compatible with valves, reliable during power outage for short period of time. The disadvantage are subject to air contaminants, air leaks, mechanical part failure due to dirt or water, subject to freezing with moisture present and control speed is limited to velocity of sound.

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Advantages of electronic systems are greater accuracy, more compatible with computer, fast signal transit time, no signal integrity loss if current loop is used. The disadvantages are contacts subject to corrosion, must be air purged, explosion proof, or intrinsically safe to be used in hazardous areas, subject to electrical interference, and more difficult to provide for positive fail-safe operation.

### Pneumatic Power Supplies

Usually known also know as instrument air system, main consideration of the system are

- i) Adequate Capacity of the air supply to all instruments in the system. Normally the capacity should maintain at sum of the individual requirements of each instrument in the system plus supplemental volume for purges, leaks, additions and etc. It estimated consumption volume of volume of 3.7 US gallons per minute for each air-consuming device is usually adequate. The air storage tank should have sufficient capacity to maintain that flow rate for five minutes or more as is considered adequate to perform an emergency shut-down of plant.
- ii) Filtering is requiring for instrument air since the contamination such as oil, water, and any hazardous or corrosive gases is not allowed. Non-lubricated compressors should be used if possible, because present of oil in compressors system may cause air contamination and may create a combustible mixture. After the compressing process instrument air will be cooled to remove the contained water. A drying system must be installed to maintain the water dew point at least 6°C below the ambient temperature at line pressure. An after filter is required to remove particulate carryover from the dehydrators.
- iii) Safety Regulation is practiced since the instrument air system is designed for high pressure (up to 59.5 psig) this means relief valve should be installed to protect the system.

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- iv) The air distribution system should be free of any “pocket” which liquid could accumulate. If the “pocket” could not be eliminated drain valve should be installed.

#### Important of Instrumentation Control for Unit Operation

When establishing a control system for a unit operation (reactor, fractionators, and fired heaters), it is very important to ensure that control of each equipment item and circuit provides the ability to maintain material balance, maintain heat balance and allow the control of product quality to the necessary degree.

Material balance control is to prevent build-up or depletion of material for continuous processes. Material balance is easily obtained in piping circuits system, since there is no place in which to store material and no storage from which to withdraw it.

In the feed circuits as in fractionation tower, material balance is obtained without automatic control. This is because whatever material is pumped into the circuit exits into the tower and the separately pressure-controlled tower acts as a pressure sink for the feed circuit. For situations in which the circuit pressure must be held higher than would be required merely because of pipe friction pressure drop, material balance is maintained through the use of a pressure controller and valve.

With this arrangement, pressure is used as a measure of material balance. Controlling the balance of material may be more difficult when variable holdup of material is possible. In these situations, a level measurement monitors buildup or depletion of liquid and is therefore the basis for control of material balance. Buildup or depletion of vapor in a tower is commonly based on pressure measurement, with many possibilities for valve location. Material balance are achieved when the pressure and bottom level are maintained in the tower.

Heat balance control is achieved when the temperature in the unit operation is maintained. In contrast to material balance, heat balance in piping circuits can become quite complex. Heat balance in the fractionation tower can be achieved by maintain of bottom temperature in towers with control the heat supply (normally steam flow rate) from

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a boiler. In this cascade control of heat balance, the success only can be achieved when level in the bottom tower is maintained, that means a material balance is achieved.

By maintaining material and heat balance in the circuits or unit operation, the product quality control can be achieved and maintained. The means of stability of the operating conditions at key points in the process will lead to successful product quality control.

The measurement of product quality is made either directly (i.e., continuously with an on-line analyzer) or indirectly (i.e., by means of a correlation). The end point of the overhead liquid product from the tower is an example. This end point may be measured directly with a boiling point device, or it may be inferred from an overhead vapor line temperature measurement. The essential point is that when laying out a control system, the basic measurement information and means for making an adjustment must be made available to the operator.

#### Process Variable Measurement Instrument

Process variable such as pressure, level, temperature, flow rate and etc, can be measured with the specific measurement instrument and control with specific control valve / control system.

Pressure measurement instruments utilized in today's market can be classified as manometer, Bourdon tubes, Bellows, diaphragm and electrical pressure transducers.

Level measurement instruments used in today's industrial processes can be classified as gauge glass, chain and tape float gauges, lever and shaft float gauges, displacer level measuring device, head-pressure level gauges, electrical type level gauges and magnetic gauge.

Temperature measurement instruments can be classified into thermocouples, resistance thermometers (RTD), and bimetallic thermometers.

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The flow rate measurement instruments can be obtained by referring to “Flow Measurement Selection and Sizing Engineering Design Guideline” and for the Control valve instrumentation can be obtained by referring to “Control Valve Selection and Sizing Engineering Design Guidelines”. Both guidelines have discussed in detail of the respective instrumentation selection and included sizing as well.

Each type of the difference process variable measurement instruments have difference design and suitability for differences process. That means the knowledge of the selection process is very important for the suitable measurement instrument for a specific process.

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## DEFINITION

**Amplifier-** A device which draws power from a source other than the input signal and which produces as an output an enlarged reproduction of the essential features of its input.

**Adaptive Control** - Method of control whereby tuning (response) of the control system is varied with the process condition, unlike other control where tuning is manual and remains constant.

**Bourdon Tube** – It uses a coiled tube which as it expands due to pressure increase causes a rotation of an arm connected to the tube.

**Capacity** - Is the water handling capability of a pump commonly expressed as either gallon per minute (gal/min) or cubic meter per minute (m<sup>3</sup>/min).

**Cascade Control** – Controllers arranged such that the output of one controller manipulates the set point input of a second controller instead of manipulating a process variable directly.

**Control Action, Derivatives (Rate)-** Control action with the controller output proportional to the rate of change of the input.

**Control Action Integral (Reset)** – Control action with the controller output proportional to the time integral of the error signal.

**Control Action, Proportional** – Control action with the controller output has a linear relationship to the error signal.

**Controller** - A device which receives a measurement of the process variable, compares that measurement with a set point representing the desired control point, and adjusts its output based on the selected control algorithm to minimize the error between the measurement and the set point. If an increase in the measured process variable above the set point causes an increase in the magnitude of the controller output, the controller is

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said to be “direct acting”. If a process variable increase above the set point causes a decrease in the magnitude of the controller output, the controller is “reverse acting”.

**Displacer** – Is a level measurement devices, displacer density will be greater than the liquid and will act as an immersed body. Operation of the displacer is based on the measurement of the change in buoyancy of the displacer as the level changes over its length.

**Distribution Control System (DCS)** – Is a system consists of some number of microprocessor-based nodes that are interconnected by a digital communications network, often called a data highway. It is type of computer process control system.

**Manometer** – Is a device to measure pressures. A common simple manometer consists of a *U* shaped tube of glass filled with some liquid. Typically the liquid is mercury because of its high density.

**PD Controller**- A controller with proportional plus derivatives (rate) control action.

**PI Controller** – A controller with proportional plus integral (reset) control action.

**PID Controller** – A controller with proportional plus integral plus derivative control action.

**RTD (Resistance Temperature Detector)** - A resistance temperature detector operates on the principle of the change in electrical resistance in wire as a function of temperature.

**RTD Element** -Sensing portion of the RTD which can be made most commonly of platinum, nickel, or copper.

**Set Point** – The desired value at which a process variable is to be controlled.

**Transmitter** – A device that converts a process measurement variable into an electrical or pneumatic signal suitable for use by an indicating or control system.

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**Thermocouple Thermometer** – Is a temperature measuring system comprising a temperature sensing element called a *thermocouple* which produces an electromotive force (emf), a device for sensing emf which includes a printed scale for converting -emf to equivalent temperature units, and *electrical conductors* for operatively connecting the two.

**Thermistor Thermometer** - Is a special type of resistor 'comprised of a mixture of metallic oxides known as semiconductors which are substances whose electrical conductivity at or near room temperature is less than that of metals but greater than that of typical insulators, Semiconductors have a high negative temperature coefficient in contrast with most metals which have a positive coefficient.

## NOMENCLATURE

A	Cross section area of body displacer, ft <sup>2</sup>
b	Length of displacer body, ft
C	Controlled Variable
c	Output bias or Manual reset
d	Thickness of flat strip, mm
E	Error = PV –SP
F <sub>B</sub>	Buoyant force, lbm.ft/s <sup>2</sup>
F <sub>G</sub>	Weight force, lbm.ft/s <sup>2</sup>
F <sub>R</sub>	Net force F <sub>B</sub> –F <sub>G</sub> , lbm.ft/s <sup>2</sup>
f	Movement of flat strip, mm
g	Acceleration of gravity, SI unit or 32.2 ft/s <sup>2</sup>
Δh	Difference height of the liquid level in manometer, SI unit
k	Specific bending coefficient, 1/°C
K <sub>i</sub>	Integral mode gain constant
K <sub>p</sub>	Proportional gain, (pure number)
L	Fluid level in tank, ft
L <sub>d</sub>	Dipped length, ft
ℓ	Height distance between points of measure P <sub>1</sub> and P <sub>2</sub> , ft
ℓ	Length of flat strip, mm

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m	Mass of the displacer body immersed in liquid, lbm
P	Absolute pressure, SI unit or Hydrostatic pressure at bottom tank, psig
P <sub>1</sub>	Absolute pressure at location 1 in tank, psig
P <sub>2</sub>	Absolute pressure at location 2 in tank, psig
P <sub>0</sub>	Atmospheric pressure, psia
P <sub>ref</sub>	Absolute pressure reference, SI unit
PB	Proportional band in percent, %
SP	Set – Point
T <sub>i</sub>	Integral mode time constant
ΔT	Temperature change, °C
K <sub>d</sub>	Derivative mode gain constant
T <sub>d</sub>	Derivative mode time constant

### Greek letters

ρ <sub>A</sub>	Density of gas or atmospheric, lbm/ft <sup>3</sup>
ρ <sub>B</sub>	Weight density of fluid in manometer, SI unit
ρ <sub>D</sub>	Density of the displacer, lbm/ft <sup>3</sup>
ρ <sub>L</sub>	Density of liquid, lbm/ft <sup>3</sup>
θ	Angle of column relative the horizontal plane
μ	Absolute (dynamic) viscosity, cp
υ <sub>1</sub>	Velocity for upstream, ft/s
υ <sub>2</sub>	Velocity for downstream, ft/s

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